

# Skewness projection pursuit: past, present and future

Skew 2026, Padua (ITALY), January 7-9, 2026

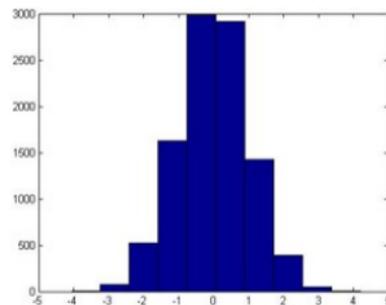
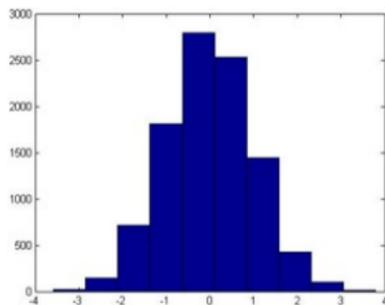
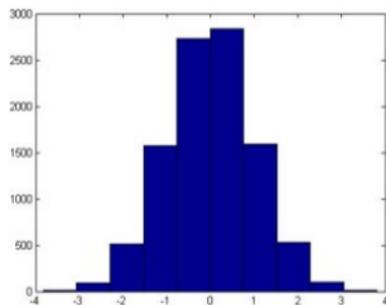
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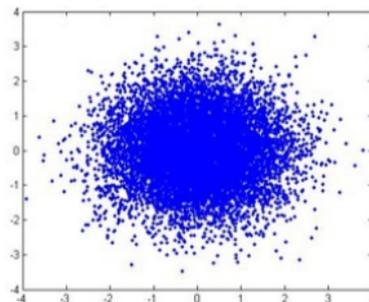
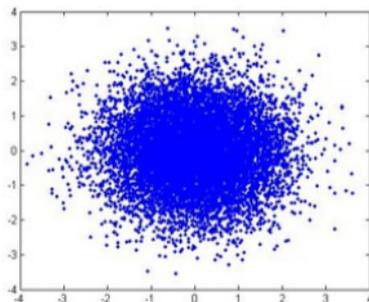
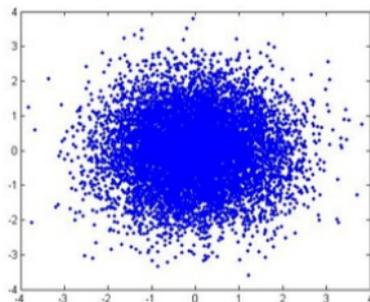
- Motivating example.
- Projection pursuit.
- Skewness optimization.
- Data example.
- Concluding remarks.

# Motivating example: histograms



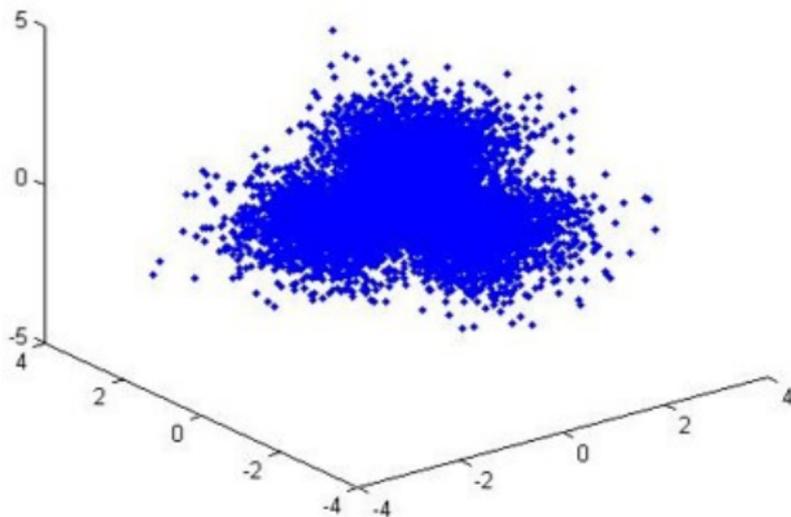
Each variable appears to be normal.

# Motivating example: scatterplots



All scatterplots hint for bivariate standard normality.

# Motivating example: 3-D plot



There seem to be three clusters.

# Motivating example: distribution

The dataset is a random sample from the density

$$2\phi(z_1)\phi(z_2)\phi(z_3)\Phi(z_1z_2z_3), \quad \phi(\cdot) = \text{pdf of } N(0,1), \quad \Phi(\cdot) = \text{cdf of } N(0,1).$$

$$\begin{array}{c} \Downarrow \\ \left( \begin{array}{c} Z_1 \\ Z_2 \end{array} \right) \sim \left( \begin{array}{c} Z_1 \\ Z_3 \end{array} \right) \sim \left( \begin{array}{c} Z_2 \\ Z_3 \end{array} \right) \sim N_2 \left\{ \left( \begin{array}{c} 0 \\ 0 \end{array} \right), \left( \begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array} \right) \right\}. \end{array}$$

## Motivating example: remarks

- Data come from a trivariate, generalized skew-normal with standard normal bivariate marginals.
- The sampled distribution is standard: its mean and covariance are a null vector and an identity matrix.
- Neither subsets of the original variables nor principal components detect the data nonnormality.

Finding a data projection which retains interesting data features.

Projection pursuit is a multivariate statistical technique aimed at finding interesting low-dimensional data projections.

# Projection pursuit: definition

$I(X)$  = projection pursuit index evaluated at the random variable  $X$ .

$\mathbf{x}$  =  $p$ -dimensional random vector.

$\mathbb{R}_0^p$  = set of all nonnull  $p$ -dimensional real vectors.

$$\text{projecting direction} = \arg \max_{\mathbf{c} \in \mathbb{R}_0^p} I(\mathbf{c}^\top \mathbf{x})$$

- **Moments:** Skewness, kurtosis, ....
- **Distances:** Kolmogorov, Euclidean, ...
- **Information:** Shannon, Fisher, ...

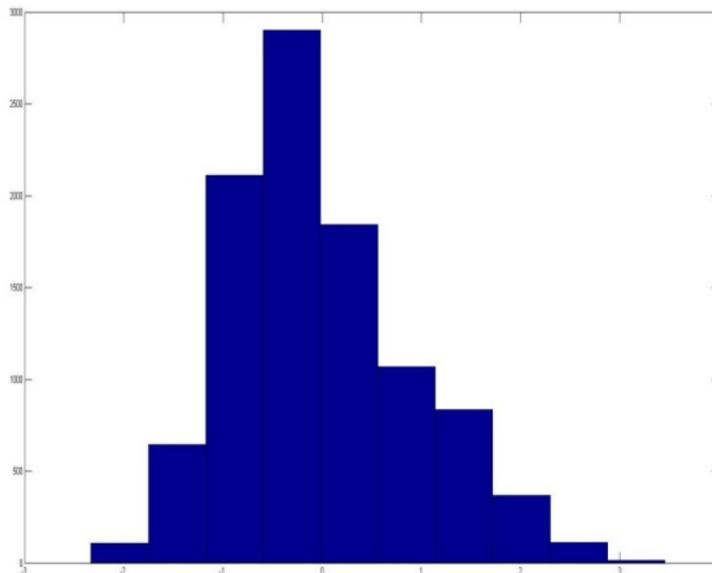
- **Normality.** The normal distribution is the least interesting.
- **Invariance.** The projection index is affinely invariant.
- **Orthogonality.** The projecting directions are mutually orthogonal.

- **Preprocessing** Remove data features which are either uninteresting, misleading or redundant.
- **Optimization** Optimize the projection pursuit index over all linear data projections, either globally or locally.
- **Removal** Remove from the data the detected interesting projections to detect other interesting projections.

Projection pursuit supports the natural aptitude of the human vision at finding patterns in data graphical displays, thus bridging the gap between human and artificial intelligence.

$$\beta_1^D(\mathbf{x}) = \max_{\mathbf{c} \in \mathbb{R}_0^p} \beta_1(\mathbf{c}^\top \mathbf{x}) = \max_{\mathbf{c} \in \mathbb{R}_0^p} \frac{\mathbb{E}^2 \left\{ (\mathbf{c}^\top \mathbf{x} - \mathbf{c}^\top \boldsymbol{\mu})^3 \right\}}{(\mathbf{c}^\top \boldsymbol{\Sigma} \mathbf{c})^3}.$$

# Skewness optimization: example



The projection which maximizes skewness clearly hints that data are skewed, but rightly does not suggest the presence of clusters.

- Skewed distributions.
- Finite mixtures.
- Independent components.

# Skewness optimization: polynomial

Skewness optimization requires the optimization of a third order polynomial in several variables, subject to a quadratic constraint:

$$\beta_1^D(\mathbf{x}) = \max_{\mathbf{c} \in \mathbb{R}_0^p} \frac{\{\mathbf{c}^\top \mathbf{\Upsilon} (\mathbf{c} \otimes \mathbf{c})\}^2}{(\mathbf{c}^\top \mathbf{\Sigma} \mathbf{c})^3},$$

$$\mathbf{\Upsilon} = \text{cos}(\mathbf{x}) = \mathbb{E} \left\{ (\mathbf{x} - \boldsymbol{\mu}) \otimes (\mathbf{x} - \boldsymbol{\mu})^\top \otimes (\mathbf{x} - \boldsymbol{\mu})^\top \right\}.$$

The directional skewness of a standardized random vector with finite third-order moments coincides with the squared dominant real tensor eigenvalue of its standardized coskewness, while the projecting direction is proportional to the associated tensor eigenvector:

$$\boldsymbol{\mu} = \mathbb{E}(\mathbf{z}) = \mathbf{0}_p, \boldsymbol{\Sigma} = \mathbb{E}(\mathbf{z}\mathbf{z}^\top) = \mathbf{I}_p, \boldsymbol{\Upsilon} = \mathbb{E}(\mathbf{z} \otimes \mathbf{z}^\top \otimes \mathbf{z}^\top),$$

$$\beta_1^D(\mathbf{z}) = \beta_1(\mathbf{c}_1^\top \mathbf{z}) = \lambda_1^2, \lambda_1 = \max_{\lambda \in \mathbb{R}} \left\{ \boldsymbol{\Upsilon}(\mathbf{c} \otimes \mathbf{c}) = \lambda \mathbf{c}, \mathbf{c}^\top \mathbf{c} = 1 \right\}.$$

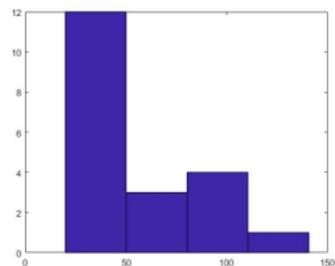
Let  $\mathbf{x}$  and  $\mathbf{v}$  be two independent and identically distributed random vectors with positive definite covariance matrices and finite third-order moments. The Mardia's skewness of  $\mathbf{x}$  ( $\mathbf{v}$ ) is

$$\beta_{1,p}(\mathbf{x}) = \mathbb{E} \left[ \left\{ (\mathbf{x} - \boldsymbol{\mu}) \boldsymbol{\Sigma}^{-1} (\mathbf{v} - \boldsymbol{\mu})^\top \right\}^3 \right].$$

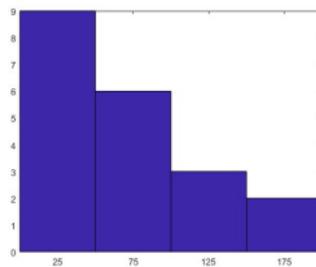
Find a  $k \times p$  full-rank matrix  $\mathbf{A}$  minimizing the Mardia's skewness of  $\mathbf{Ax}$ , for a given value of  $k < p$ .

- Sources: Transfermarkt and Capology.
- Units: 20 major Italian football teams.
- Variables: Salaries, Acquisitions, Expenses.

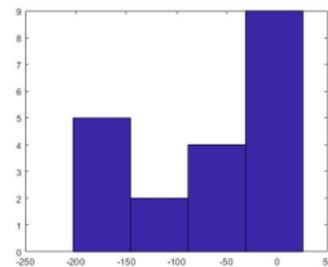
# Data example: histograms



Salaries

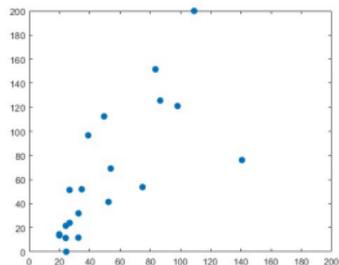


Acquisitions

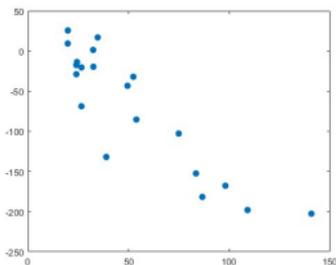


Expenses

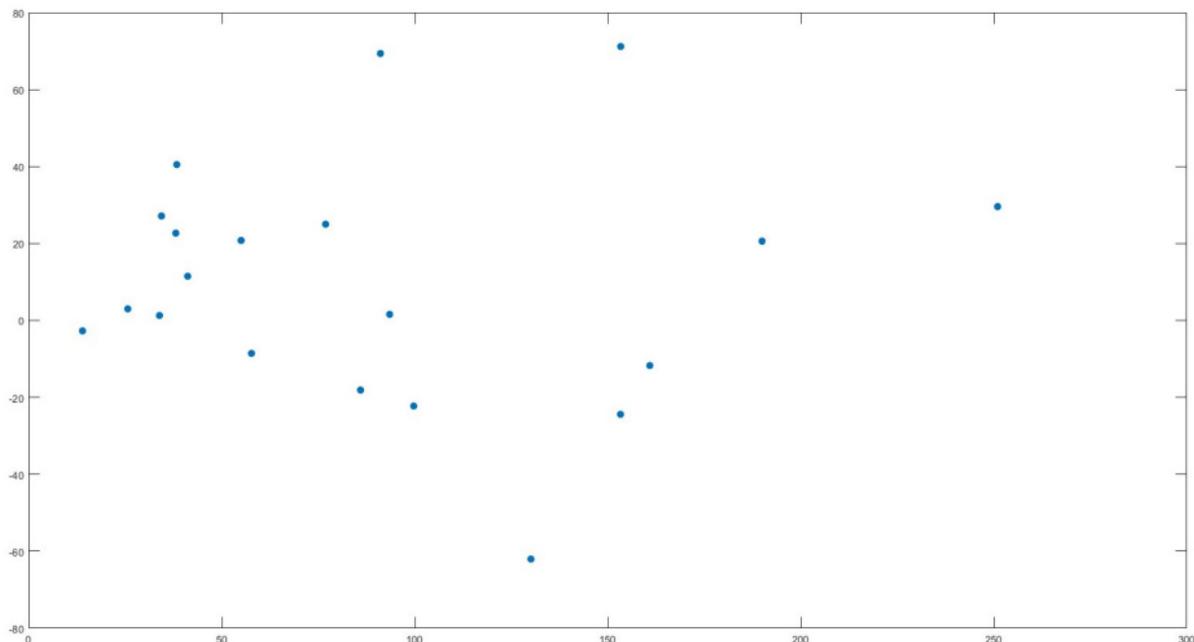
# Data example: scatterplots



Salaries and Acquisitions

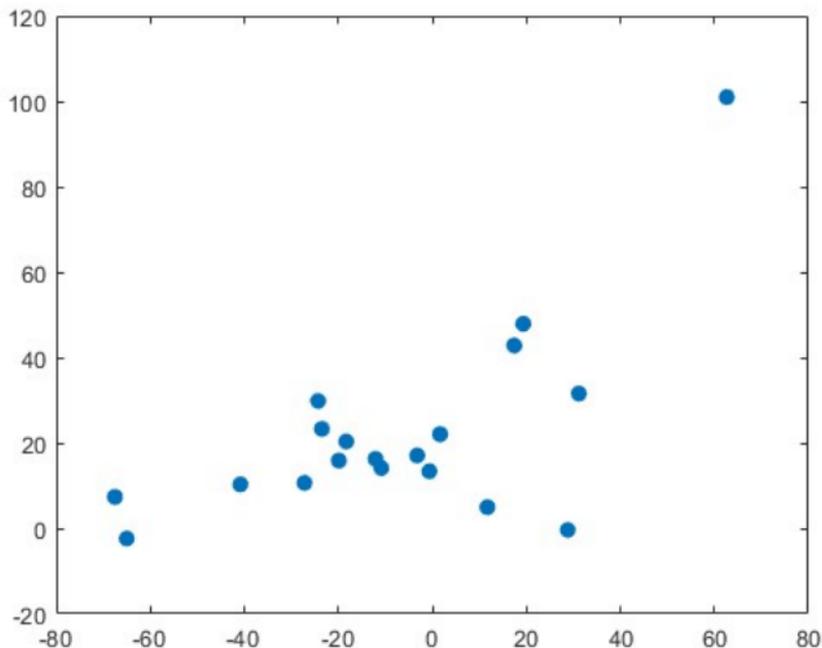


# Data example: principal components



Scatterplot of the first and second principal components, accounting for more than 93% of the total variance.

# Data example: skewness optimization



Scatterplot of the projections with minimal and maximal absolute skewnesses.

- The scatterplot obtained via skewness optimization hints for the presence of an outlier: the Inter football team, which came second in the last Italian Football Championship.
- Other scatterplots obtained via projection pursuit, including the one based on kurtosis optimization (projections with minimal and maximal kurtoses), led to similar results.
- The principal component scatterplot did not suggest the presence of the potential outlier, despite accounting for about 93% of the total variance.

Skewness projection pursuit originated as an exploratory, data-based technique later has been successfully applied to (semi)parametric models.

- In which skewed models does SPP have a simple, interpretable form?
- Does SPP overcome some limitations of likelihood inference?
- Is there any scope for projection pursuit in Bayesian inference?

The literature on the sampling properties of skewness projection pursuit (SPP) is quite limited.

- The sampling distribution of SPP is related to the maxima of Gaussian random fields.
- Sampling properties of SPP have been investigated using the tube method.
- Is the asymptotic distribution of directional skewness under normality skew-normal?

The widespread use of (skewness) projection pursuit has been hampered by computational difficulties.

- Algorithms.
- Packages.
- Simulations.

The literature on tensor eigenpairs is very limited and contains some wrong statements.

- Under which conditions tensor eigenpairs are real? .
- How many eigenpairs does a given tensor have?
- Assessing the multiplicity of tensor eigenvalues.

Projection pursuit poses additional problems when there are more variables than units.

- Data preprocessing for dimension reduction .
- Variable selection via projection pursuit.
- Generalized tensor eigenpairs to address singularities.

The performance of SPP crucially depends on the structure of the multivariate third cumulant of the underlying distribution.

- Tensor rank of the third cumulant.
- Infinite third-order moments.
- Skewed distributions with null third cumulants.

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YOUR ATTENTION!